



## Notation

### EQUATION OF MOTION FOR ORTHOTROPIC RECTANGULAR PLATE

$$D_1 \frac{\partial^4 w(x, y, t)}{\partial x^4} + 2D_3 \frac{\partial^4 w(x, y, t)}{\partial x^2 \partial y^2} + D_2 \frac{\partial^4 w(x, y, t)}{\partial y^4} + \rho h \frac{\partial^2 w(x, y, t)}{\partial t^2} = 0$$

$$D_1 = \frac{E_1 h^3}{12(1-\vartheta_{12}\vartheta_{21})}, D_2 = \frac{E_2 h^3}{12(1-\vartheta_{12}\vartheta_{21})}, D_{66} = \frac{G_{12} h^3}{12}, D_3 = D_{12} + 2D_{66}, D_{12} = \vartheta_{12} D_2 = \vartheta_{21} D_1$$

If  $E_1 = E_2 = E$  &  $\vartheta_{12} = \vartheta_{21} = \vartheta$ ,

$$D_1 = D_2 = \frac{Eh^3}{12(1-\vartheta^2)} = D \text{ \& } D_3 = D_{12} + 2D_{66} = \frac{\vartheta Eh^3}{12(1-\vartheta^2)} + 2 \frac{Eh^3}{12 \cdot 2 \cdot (1-\vartheta)} = \frac{Eh^3}{12(1-\vartheta^2)} = D$$

Then Isotropic Homogeneous case

$$D \Delta \Delta w(x, y, t) + \rho h \frac{\partial^2 w(x, y, t)}{\partial t^2} = 0$$

## Eigenfunction 2

### SEPARATION OF VARIABLES

$$w(x, y, t) = \Phi(x)\psi(y)(A\cos(\omega t) + B\sin(\omega t))$$

Then

$$D_1 \frac{\partial^4 \Phi(x)}{\partial x^4} \psi(y) + 2D_3 \frac{\partial^4 \Phi(x)\psi(y)}{\partial x^2 \partial y^2} + D_2 \frac{\partial^4 \psi(y)}{\partial y^4} \Phi(x) - \beta^4 \Phi(x)\psi(y) = 0$$

$$\text{Which } \beta^4 = \omega^2 \rho h$$

In order for the separation occur,

$$\frac{\partial^2 \Phi(x)}{\partial x^2} = -\mu^2 \Phi(x) \quad \& \quad \frac{\partial^2 \psi(y)}{\partial y^2} = -\lambda^2 \psi(y)$$

$$\Rightarrow \Phi(x) = Ae^{\mu x} \quad \& \quad \psi(y) = Be^{\lambda y}$$

Then

$$D_1 \mu^4 + 2D_3 \mu^2 \lambda^2 + D_2 \lambda^4 - \beta^4 = 0$$

## Eigenfunction 2

### ROOTS

$$\mu_{1,2} = \pm i^2 \sqrt{\varepsilon_1 + \delta_1} \equiv \pm i \alpha_1 \quad \& \quad \mu_{3,4} = \pm^2 \sqrt{\varepsilon_1 - \delta_1} \equiv \pm \beta_1$$

$$\varepsilon_1 = \sqrt{\lambda^4 \left[ \left( \frac{D_3}{D_1} \right)^2 - \frac{D_1}{D_2} \right] + \frac{\beta^4}{D_1}} \quad \& \quad \delta_1 = \lambda^2 \frac{D_3}{D_1}$$

$$\lambda_{1,2} = \pm i^2 \sqrt{\varepsilon_2 + \delta_2} \equiv \pm i \alpha_2 \quad \& \quad \lambda_{3,4} = \pm^2 \sqrt{\varepsilon_2 - \delta_2} \equiv \pm \beta_2$$

$$\varepsilon_2 = \sqrt{\mu^4 \left[ \left( \frac{D_3}{D_2} \right)^2 - \frac{D_2}{D_1} \right] + \frac{\beta^4}{D_2}} \quad \& \quad \delta_2 = \mu^2 \frac{D_3}{D_2}$$

At the same time

$$\alpha_2 = \sqrt{\sqrt{\alpha_1^4 \left[ \left( \frac{D_3}{D_2} \right)^2 - \frac{D_2}{D_1} \right] + \frac{\beta^4}{D_2}} - \alpha_1^2 \frac{D_3}{D_2}} \quad \& \quad \beta_2 = \sqrt{\sqrt{\alpha_1^4 \left[ \left( \frac{D_3}{D_2} \right)^2 - \frac{D_2}{D_1} \right] + \frac{\beta^4}{D_2}} + \alpha_1^2 \frac{D_3}{D_2}}$$

$$(\alpha_1^2 + \beta_1^2)^2 + \frac{D_1 D_2 - D_3^2}{D_3^2} (\alpha_1^2 - \beta_1^2)^2 = \frac{4\beta^4}{D_1}$$

## Eigenfunction 2

### SOLUTION

$$\begin{aligned}\Phi(x) &= A_1 \cos \alpha_1 x + B_1 \sin \alpha_1 x + C_1 \cosh \beta_1 x + H_1 \sinh \beta_1 x \\ \psi(y) &= A_2 \cos \alpha_2 y + B_2 \sin \alpha_2 y + C_2 \cosh \beta_2 y + H_2 \sinh \beta_2 y\end{aligned}$$

Boundary conditions:

In x direction:

$$\begin{aligned}w(0, y) = 0 &\Rightarrow \Phi(0) = 0 \\ w(a, 0) = 0 &\Rightarrow \Phi(a) = 0 \\ \frac{\partial w(0, y)}{\partial x} = 0 &\Rightarrow \frac{\partial \Phi(0)}{\partial x} = 0 \\ \frac{\partial w(a, y)}{\partial x} = 0 &\Rightarrow \frac{\partial \Phi(a)}{\partial x} = 0\end{aligned}$$

The same in y direction

$$\begin{aligned}A_1 &= -C_1 \\ \alpha_1 B_1 &= -\beta_1 H_1 \\ H_1 &= -k_2 C_1\end{aligned}\quad \text{with } k_2 = \frac{\cos \alpha_1 a - \cosh \beta_1 a}{(\beta_1 / \alpha_1) \sin \alpha_1 a - \sinh \beta_1 a}$$

## Eigenfunction 2

### NORMAL EIGENFUNCTIONS

Assuming  $C_1 = 1$

$$\Phi(x) = -\cos\alpha_1 x + (\beta_1/\alpha_1)k_2 \sin\alpha_1 x + \cosh\beta_1 x - k_2 \sinh\beta_1 x$$

The same for y direction

$$\psi(y) = -\cos\alpha_2 y + (\beta_2/\alpha_2)k_1 \sin\alpha_2 y + \cosh\beta_2 y - k_1 \sinh\beta_2 y$$

### ORTHOGONALITY?!

Use the same re-orthogonalisation process of eigenfunction 1

## Eigenfunction 2

### PROOF OF NORMAL EIGENFUNCTIONS

$$w(x, y, t) = \Phi(x)\psi(y)$$

Then for the eigenfunction:

$$D_1 \frac{\partial^4 \Phi(x)}{\partial x^4} \psi(y) + 2D_3 \frac{\partial^4 \Phi(x)\psi(y)}{\partial x^2 \partial y^2} + D_2 \frac{\partial^4 \psi(y)}{\partial y^4} \Phi(x) - \delta \cdot \Phi(x)\psi(y) = 0$$

In order for the separation occur,

$$\frac{\partial^2 \Phi(x)}{\partial x^2} = -\mu^2 \Phi(x) \quad \& \quad \frac{\partial^2 \psi(y)}{\partial y^2} = -\lambda^2 \psi(y)$$

$$\Rightarrow \Phi(x) = Ae^{\mu x} \quad \& \quad \psi(y) = Be^{\lambda y}$$

Then

$$D_1 \mu^4 + 2D_3 \mu^2 \lambda^2 + D_2 \lambda^4 - \delta = 0$$

## Eigenfunction 2

### PROOF OF NORMAL EIGENFUNCTIONS

$$\mu_{1,2} = \pm i^2 \sqrt{\varepsilon_1 + \delta_1} \equiv \pm i \alpha_1 \quad \& \quad \mu_{3,4} = \pm^2 \sqrt{\varepsilon_1 - \delta_1} \equiv \pm \beta_1$$

$$\varepsilon_1 = \sqrt{\lambda^4 \left[ \left( \frac{D_3}{D_1} \right)^2 - \frac{D_1}{D_2} \right] + \frac{\delta}{D_1}} \quad \& \quad \delta_1 = \lambda^2 \frac{D_3}{D_1}$$

$$\lambda_{1,2} = \pm i^2 \sqrt{\varepsilon_2 + \delta_2} \equiv \pm i \alpha_2 \quad \& \quad \lambda_{3,4} = \pm^2 \sqrt{\varepsilon_2 - \delta_2} \equiv \pm \beta_2$$

$$\varepsilon_2 = \sqrt{\mu^4 \left[ \left( \frac{D_3}{D_2} \right)^2 - \frac{D_2}{D_1} \right] + \frac{\delta}{D_2}} \quad \& \quad \delta_2 = \mu^2 \frac{D_3}{D_2}$$

At the same time

$$\alpha_2 = \sqrt{\sqrt{\alpha_1^4 \left[ \left( \frac{D_3}{D_2} \right)^2 - \frac{D_2}{D_1} \right] + \frac{\delta}{D_2}} - \alpha_1^2 \frac{D_3}{D_2}} \quad \& \quad \beta_2 = \sqrt{\sqrt{\alpha_1^4 \left[ \left( \frac{D_3}{D_2} \right)^2 - \frac{D_2}{D_1} \right] + \frac{\delta}{D_2}} + \alpha_1^2 \frac{D_3}{D_2}}$$

$$(\alpha_1^2 + \beta_1^2)^2 + \frac{D_1 D_2 - D_3^2}{D_3^2} (\alpha_1^2 - \beta_1^2)^2 = \frac{4\delta}{D_1}$$



## Eigenfunction 2

### PROOF OF NORMAL EIGENFUNCTIONS

$$\begin{aligned}\Phi(x) &= A_1 \cos \alpha_1 x + B_1 \sin \alpha_1 x + C_1 \cosh \beta_1 x + H_1 \sinh \beta_1 x \\ \psi(y) &= A_2 \cos \alpha_2 y + B_2 \sin \alpha_2 y + C_2 \cosh \beta_2 y + H_2 \sinh \beta_2 y\end{aligned}$$

Boundary conditions:

In x direction:

$$\begin{aligned}w(0, y) = 0 &\Rightarrow \Phi(0) = 0 \\ w(a, 0) = 0 &\Rightarrow \Phi(a) = 0 \\ \frac{\partial w(0, y)}{\partial x} = 0 &\Rightarrow \frac{\partial \Phi(0)}{\partial x} = 0 \\ \frac{\partial w(a, y)}{\partial x} = 0 &\Rightarrow \frac{\partial \Phi(a)}{\partial x} = 0\end{aligned}$$

The same in y direction

$$\begin{aligned}A_1 &= -C_1 \\ \alpha_1 B_1 &= -\beta_1 H_1 \\ H_1 &= -k_2 C_1\end{aligned}\quad \text{with } k_2 = \frac{\cos \alpha_1 a - \cosh \beta_1 a}{(\beta_1 / \alpha_1) \sin \alpha_1 a - \sinh \beta_1 a}$$

## Eigenfunction 2

### PROOF OF NORMAL EIGENFUNCTIONS

Assuming  $C_1 = 1$

$$\Phi(x) = -\cos\alpha_1 x + (\beta_1/\alpha_1)k_2 \sin\alpha_1 x + \cosh\beta_1 x - k_2 \sinh\beta_1 x$$

The same for y direction

$$\psi(y) = -\cos\alpha_2 y + (\beta_2/\alpha_2)k_1 \sin\alpha_2 y + \cosh\beta_2 y - k_1 \sinh\beta_2 y$$

## Eigenfunction 2

### PROOF OF NORMAL EIGENFUNCTIONS

$$\Phi_1 = A_1 \cos \alpha_1 x + B_1 \sin \alpha_1 x, \quad \Phi_2 = C_1 \cosh \beta_1 x + H_1 \sinh \beta_1 x$$

$$\psi_1 = A_2 \cos \alpha_2 y + B_2 \sin \alpha_2 y, \quad \psi_2 = C_2 \cosh \beta_2 y + H_2 \sinh \beta_2 y$$

$$\Phi(x) = \Phi_1 + \Phi_2, \quad \psi(y) = \psi_1 + \psi_2$$

$$D_1 \frac{\partial^4 \Phi(x)}{\partial x^4} \psi(y) = D_1 \frac{\partial^4 (\Phi_1 + \Phi_2)}{\partial x^4} (\psi_1 + \psi_2) = D_1 (\alpha_1^4 \Phi_1 + \beta_1^4 \Phi_2) (\psi_1 + \psi_2)$$

$$2D_3 \frac{\partial^4 w(x, y, t)}{\partial x^2 \partial y^2} = 2D_3 \frac{\partial^4 (\Phi_1 + \Phi_2) (\psi_1 + \psi_2)}{\partial x^2 \partial y^2} = 2D_3 (\alpha_1^2 \alpha_2^2 \Phi_1 \psi_1 - \alpha_1^2 \beta_2^2 \Phi_1 \psi_2 - \beta_1^2 \alpha_2^2 \Phi_2 \psi_1 + \beta_1^2 \beta_2^2 \Phi_2 \psi_2)$$

$$D_2 \frac{\partial^4 \psi(y)}{\partial y^4} \Phi(x) = D_2 \frac{\partial^4 (\psi_1 + \psi_2)}{\partial y^4} (\Phi_1 + \Phi_2) = D_2 (\Phi_1 + \Phi_2) (\alpha_2^4 \psi_1 + \beta_2^4 \psi_2)$$

$$\begin{aligned} & D_1 \frac{\partial^4 \Phi(x)}{\partial x^4} \psi(y) + 2D_3 \frac{\partial^4 \Phi(x) \psi(y)}{\partial x^2 \partial y^2} + D_2 \frac{\partial^4 \psi(y)}{\partial y^4} \Phi(x) \\ &= (D_1 \alpha_1^4 + 2D_3 \alpha_1^2 \alpha_2^2 + D_2 \alpha_2^4) \Phi_1 \psi_1 + (D_1 \alpha_1^4 - 2D_3 \alpha_1^2 \beta_2^2 + D_2 \beta_2^4) \Phi_1 \psi_2 \\ &+ (D_1 \beta_1^4 - 2D_3 \beta_1^2 \alpha_2^2 + D_2 \alpha_2^4) \Phi_2 \psi_1 + (D_1 \beta_1^4 + 2D_3 \beta_1^2 \beta_2^2 + D_2 \beta_2^4) \Phi_2 \psi_2 \end{aligned}$$

## Eigenfunction 2

### PROOF OF NORMAL EIGENFUNCTIONS

$$\alpha_2 = \sqrt{\sqrt{\alpha_1^4 \left[ \left( \frac{D_3}{D_2} \right)^2 - \frac{D_2}{D_1} \right] + \frac{\delta}{D_2}} - \alpha_1^2 \frac{D_3}{D_2}} \quad \& \quad \beta_2 = \sqrt{\sqrt{\alpha_1^4 \left[ \left( \frac{D_3}{D_2} \right)^2 - \frac{D_2}{D_1} \right] + \frac{\delta}{D_2}} + \alpha_1^2 \frac{D_3}{D_2}}$$

$$\alpha_2 = \sqrt{\sqrt{\beta_1^4 \left[ \left( \frac{D_3}{D_2} \right)^2 - \frac{D_1}{D_2} \right] + \frac{\delta}{D_2}} - \beta_1^2 \frac{D_3}{D_2}} \quad \& \quad \beta_2 = \sqrt{\sqrt{\beta_1^4 \left[ \left( \frac{D_3}{D_2} \right)^2 - \frac{D_1}{D_2} \right] + \frac{\delta}{D_2}} + \beta_1^2 \frac{D_3}{D_2}}$$

$$(D_1 \alpha_1^4 + 2D_3 \alpha_1^2 \alpha_2^2 + D_2 \alpha_2^4) = \delta$$

$$(D_1 \alpha_1^4 - 2D_3 \alpha_1^2 \beta_2^2 + D_2 \beta_2^4) = \delta$$

$$(D_1 \beta_1^4 - 2D_3 \beta_1^2 \alpha_2^2 + D_2 \alpha_2^4) = \delta$$

$$(D_1 \beta_1^4 + 2D_3 \beta_1^2 \beta_2^2 + D_2 \beta_2^4) = \delta$$

## Eigenfunction 2

### PROOF OF NORMAL EIGENFUNCTIONS

$$D_1 \frac{\partial^4 \Phi(x)}{\partial x^4} \psi(y) + 2D_3 \frac{\partial^4 \Phi(x) \psi(y)}{\partial x^2 \partial y^2} + D_2 \frac{\partial^4 \psi(y)}{\partial y^4} \Phi(x) = \delta (\Phi_1 \psi_1 + \Phi_1 \psi_2 + \Phi_2 \psi_1 + \Phi_2 \psi_2)$$

$$D_1 \frac{\partial^4 \Phi(x)}{\partial x^4} \psi(y) + 2D_3 \frac{\partial^4 \Phi(x) \psi(y)}{\partial x^2 \partial y^2} + D_2 \frac{\partial^4 \psi(y)}{\partial y^4} \Phi(x) = \delta \Phi(x) \psi(y)$$

$$\text{Which } \delta = \beta^4 = \omega^2 \rho h$$

## Eigenfunction 2

### PROOF OF SELF-ADJOINT OPERATOR

$$L = D_1 \frac{\partial^4}{\partial x^4} + 2D_3 \frac{\partial^4}{\partial x^2 \partial y^2} + D_2 \frac{\partial^4}{\partial y^4}$$

Assuming  $w_1$  &  $w_2$  two function satisfy  $Lw = \lambda w$  and the boundary conditions  $w = \frac{\partial w}{\partial x} = 0$  for  $x=0,a$  and  $w = \frac{\partial w}{\partial y} = 0$  for  $y=0,b$

$$\langle Lu, v \rangle = \iint Lu \cdot v dx dy$$

$$\langle Lu, v \rangle = \langle u, Lv \rangle ?$$

$$\begin{aligned} \iint \frac{\partial^4 w_1}{\partial x^4} w_2 dx dy &= \int \left[ \frac{\partial^3 w_1}{\partial x^3} w_2 \Big|_{x=0,a} - \int \left( \frac{\partial^3 w_1}{\partial x^3} \frac{\partial w_2}{\partial x} \right) dx \right] dy = - \int \left[ \int \left( \frac{\partial^3 w_1}{\partial x^3} \frac{\partial w_2}{\partial x} \right) dx \right] dy \\ &= - \int \left[ \frac{\partial^2 w_1}{\partial x^2} \frac{\partial w_2}{\partial x} \Big|_{x=0,a} - \int \left( \frac{\partial^2 w_1}{\partial x^2} \frac{\partial^2 w_2}{\partial x^2} \right) dx \right] dy = \int \left[ \int \left( \frac{\partial^2 w_1}{\partial x^2} \frac{\partial^2 w_2}{\partial x^2} \right) dx \right] dy \\ &= \int \left[ \frac{\partial w_1}{\partial x} \frac{\partial^2 w_2}{\partial x^2} \Big|_{x=0,a} - \int \left( \frac{\partial w_1}{\partial x} \frac{\partial^3 w_2}{\partial x^3} \right) dx \right] dy = - \int \left[ \int \left( \frac{\partial w_1}{\partial x} \frac{\partial^3 w_2}{\partial x^3} \right) dx \right] dy = - \int \left[ w_1 \frac{\partial^3 w_2}{\partial x^3} \Big|_{x=0,a} - \int \left( w_1 \frac{\partial^4 w_2}{\partial x^4} \right) dx \right] dy \\ &= \iint w_1 \frac{\partial^4 w_2}{\partial x^4} dx dy \end{aligned}$$

In the same process,  $\iint \frac{\partial^4 w_1}{\partial y^4} w_2 dx dy = \iint w_1 \frac{\partial^4 w_2}{\partial y^4} dx dy$

## Eigenfunction 2

### PROOF OF SELF-ADJOINT OPERATOR

$$\begin{aligned} \int \int \frac{\partial^4 w_1}{\partial x^2 \partial y^2} w_2 \, dx dy &= \int \left[ \frac{\partial^3 w_1}{\partial x \partial y^2} w_2 \Big|_{x=0,a} - \int \left( \frac{\partial^3 w_1}{\partial x \partial y^2} \frac{\partial w_2}{\partial x} \right) dx \right] dy = - \int \left[ \int \left( \frac{\partial^3 w_1}{\partial x \partial y^2} \frac{\partial w_2}{\partial x} \right) dx \right] dy \\ &= - \int \left[ \frac{\partial^2 w_1}{\partial y^2} \frac{\partial w_2}{\partial x} \Big|_{x=0,a} - \int \left( \frac{\partial^2 w_1}{\partial y^2} \frac{\partial^2 w_2}{\partial x^2} \right) dx \right] dy = \int \int \frac{\partial^2 w_1}{\partial y^2} \frac{\partial^2 w_2}{\partial x^2} \, dx dy = \dots = \int \int w_1 \frac{\partial^4 w_2}{\partial x^2 \partial y^2} \, dx dy \end{aligned}$$

So

$$\langle Lw_1, w_2 \rangle = \langle w_1, L^* w_2 \rangle \quad \& L = L^*$$

$$\text{with } \langle Lu, v \rangle = \iint Lu \cdot v \, dx dy$$

Then

$$\langle Lw_n, w_m \rangle - \langle w_n, Lw_m \rangle = 0$$

$$\langle \lambda_n - \lambda_m \rangle \cdot \langle w_n, w_m \rangle = 0$$

$$\lambda_n - \lambda_m \neq 0 \Rightarrow \langle w_n, w_m \rangle = 0$$

## Notation

### EQUATION OF MOTION FOR ORTHOTROPIC RECTANGULAR PLATE

$$D_1 \frac{\partial^4 w(x, y, t)}{\partial x^4} + 2D_3 \frac{\partial^4 w(x, y, t)}{\partial x^2 \partial y^2} + D_2 \frac{\partial^4 w(x, y, t)}{\partial y^4} + \rho h \frac{\partial^2 w(x, y, t)}{\partial t^2} = 0$$

$$D_1 = \frac{E_1 h^3}{12(1-\vartheta_{12}\vartheta_{21})}, D_2 = \frac{E_2 h^3}{12(1-\vartheta_{12}\vartheta_{21})}, D_{66} = \frac{G_{12} h^3}{12}, D_3 = D_{12} + 2D_{66}, D_{12} = \vartheta_{12} D_2 = \vartheta_{21} D_1$$

If  $E_1 = E_2 = E$  &  $\vartheta_{12} = \vartheta_{21} = \vartheta$ ,

$$D_1 = D_2 = \frac{Eh^3}{12(1-\vartheta^2)} = D \text{ \& } D_3 = D_{12} + 2D_{66} = \frac{\vartheta Eh^3}{12(1-\vartheta^2)} + 2 \frac{Eh^3}{12 \cdot 2 \cdot (1-\vartheta)} = \frac{Eh^3}{12(1-\vartheta^2)} = D$$

Then Isotropic Homogeneous case

$$D \Delta \Delta w(x, y, t) + \rho h \frac{\partial^2 w(x, y, t)}{\partial t^2} = 0$$



## Eigenfunction 3

### SOLUTION FOR HOMOGENOUS ISOTROPIC CASE

$$w(x, y, t) = \Phi(x)\psi(y)$$

Then

$$\frac{\partial^4 \Phi(x)}{\partial x^4} \psi(y) + 2 \frac{\partial^4 \Phi(x) \psi(y)}{\partial x^2 \partial y^2} + \frac{\partial^4 \psi(y)}{\partial y^4} \Phi(x) = 0$$

$$\Rightarrow \Phi(x) = Ae^{\alpha x} \text{ \& } \psi(y) = Be^{\beta y}$$

Then

$$\alpha^4 + 2\alpha^2\beta^2 + \beta^4 = 0$$

So

$$\alpha^2_{1,2} = -\beta^2 \text{ or } \beta^2_{1,2} = -\alpha^2$$

$$\alpha = i\beta, \alpha = -i\beta$$

$$\alpha = -i\beta, \alpha = i\beta \Rightarrow \beta = i\alpha, \beta = -i\alpha$$

## Eigenfunction 3

### SOLUTION FOR HOMOGENOUS ISOTROPIC CASE

The general solution

$$\begin{aligned}
 w(x, y, t) &= (C + Dx)e^{\beta ix} \cdot Be^{\beta y} + (E + Fy)e^{i\alpha y} \cdot Ae^{\alpha x} \\
 &= (C + Dx)e^{\alpha x} \cdot Be^{i\alpha y} + (E + Fy)e^{\beta y} \cdot Ae^{i\beta x} \\
 &= B(C + Dx)(\sinh(\alpha x) + \cosh(\alpha x)) \cdot (\sin(\alpha y) + \cos(\alpha y)) \\
 &\quad + A(E + Fy)(\sinh(\beta y) + \cosh(\beta y)) \cdot (\sin(\beta x) + \cos(\beta x)) \\
 &= \sin(\alpha y) B(C + Dx)(\sinh(\alpha x) + \cosh(\alpha x)) \\
 &\quad + \cos(\alpha y) B(C + Dx)(\sinh(\alpha x) + \cosh(\alpha x)) \\
 &\quad \sin(\beta x) A(E + Fy)(\sinh(\beta y) + \cosh(\beta y)) \\
 &\quad + \cos(\beta x) A(E + Fy)(\sinh(\beta y) + \cosh(\beta y)) \\
 &= \sin(\alpha y) [B(C + Dx) \sinh(\alpha x) + B(C + Dx) \cosh(\alpha x)] \\
 &\quad + \cos(\alpha y) [B(C + Dx) \sinh(\alpha x) + B(C + Dx) \cosh(\alpha x)] \\
 &\quad + \sin(\beta x) [A(E + Fy) \sinh(\beta y) + A(E + Fy) \cosh(\beta y)] \\
 &\quad + \cos(\beta x) [A(E + Fy) \sinh(\beta y) + A(E + Fy) \cosh(\beta y)]
 \end{aligned}$$

Airy Stress Function approach form

## Eigenfunction 2

### EIGENFUNCTIONS TEST

If  $w = Ae^{\alpha x} Be^{\beta y}$  is a solution,  $w = Axe^{\alpha x} Be^{\beta y}$  is also a solution?  $w = Aye^{\alpha x} Be^{\beta y}$  or  $w = Axye^{\alpha x} Be^{\beta y}$ ?  $w = Ax^2e^{\alpha x} Be^{\beta y}$ ,  $w = Ay^2e^{\alpha x} Be^{\beta y}$  etc.

$$1) w = Axe^{\alpha x} Be^{\beta y}$$

$$\frac{\partial^4 w}{\partial x^4} = 4\alpha^3 Ae^{\alpha x} Be^{\beta y} + 4\alpha^4 x Ae^{\alpha x} Be^{\beta y}$$

$$2 \frac{\partial^4 w}{\partial x^2 \partial y^2} = 2(2\alpha\beta^2 Ae^{\alpha x} Be^{\beta y} + \alpha^2 \beta^2 x Ae^{\alpha x} Be^{\beta y})$$

$$\frac{\partial^4 w}{\partial y^4} = \beta^4 x Ae^{\alpha x} Be^{\beta y}$$

$$\Delta\Delta w = \lambda w \Rightarrow 4\alpha^3 = -4\alpha\beta^2$$

$$\Rightarrow \alpha^2 = -\beta^2$$

$$\alpha = i\beta, \alpha = i\beta$$

$$\alpha = -i\beta, \alpha = -i\beta$$

## Eigenfunction 2

### EIGENFUNCTIONS TEST

If  $w = Ae^{\alpha x} Be^{\beta y}$  is a solution,  $w = Axe^{\alpha x} Be^{\beta y}$  is also a solution?  $w = Ax^2e^{\alpha x} Be^{\beta y}$  or  $w = Aye^{\alpha x} Be^{\beta y}$ ?  $w = Ay^2e^{\alpha x} Be^{\beta y}$   $w = Axye^{\alpha x} Be^{\beta y}$  etc.

$$1) w = Ax^2e^{\alpha x} Be^{\beta y}$$

$$\frac{\partial^4 w}{\partial x^4} = 12\alpha^3 Ae^{\alpha x} Be^{\beta y} + 8\alpha^3 x Ae^{\alpha x} Be^{\beta y} + \alpha^4 x^2 Ae^{\alpha x} Be^{\beta y}$$

$$2 \frac{\partial^4 w}{\partial x^2 \partial y^2} = 2(2\beta^2 Ae^{\alpha x} Be^{\beta y} + 4\alpha\beta^2 x Ae^{\alpha x} Be^{\beta y} + \alpha^2 \beta^2 x^2 Ae^{\alpha x} Be^{\beta y})$$

$$\frac{\partial^4 w}{\partial y^4} = \beta^4 x^2 Ae^{\alpha x} Be^{\beta y}$$

$$\Delta\Delta w = \lambda w \Rightarrow \begin{cases} 12\alpha^2 = -4\beta^2 \\ 8\alpha^3 = -8\alpha\beta^2 \end{cases}$$

$$\Rightarrow \begin{cases} 3\alpha^2 = -\beta^2 \\ \alpha^2 = -\beta^2 \end{cases}$$

## Eigenfunction 2

### EIGENFUNCTIONS TEST

If  $w = Ae^{\alpha x} Be^{\beta y}$  is a solution,  $w = Axe^{\alpha x} Be^{\beta y}$  is also a solution?  $w = Ax^2e^{\alpha x} Be^{\beta y}$  or  $w = Aye^{\alpha x} Be^{\beta y}$ ?  $w = Ay^2e^{\alpha x} Be^{\beta y}$   $w = Axye^{\alpha x} Be^{\beta y}$  etc.

$$1) w = Ax^3e^{\alpha x} Be^{\beta y}$$

$$\frac{\partial^4 w}{\partial x^4} = 24\alpha Ae^{\alpha x} Be^{\beta y} + 36\alpha^2 x Ae^{\alpha x} Be^{\beta y} + 12\alpha^3 x^2 Ae^{\alpha x} Be^{\beta y} + \alpha^4 x^3 Ae^{\alpha x} Be^{\beta y}$$

$$2 \frac{\partial^4 w}{\partial x^2 \partial y^2} = 2(6\beta^2 x Ae^{\alpha x} Be^{\beta y} + 6\alpha\beta^2 x^2 Ae^{\alpha x} Be^{\beta y} + \alpha^2\beta^2 x^3 Ae^{\alpha x} Be^{\beta y})$$

$$\frac{\partial^4 w}{\partial y^4} = \beta^4 x^3 Ae^{\alpha x} Be^{\beta y}$$

$$\Delta\Delta w \neq \lambda w$$

Conclusion:

$Ae^{\alpha x} Be^{\beta y}$ ,  $Axe^{\alpha x} Be^{\beta y}$ ,  $Aye^{\alpha x} Be^{\beta y}$ ,  $Ay^2e^{\alpha x} Be^{\beta y}$ ,  $AxYe^{\alpha x} Be^{\beta y}$ ,  $Ax^2e^{\alpha x} Be^{\beta y}$  etc. can not form a basis of the plate's eigenfunction.

## Eigenfunction 2

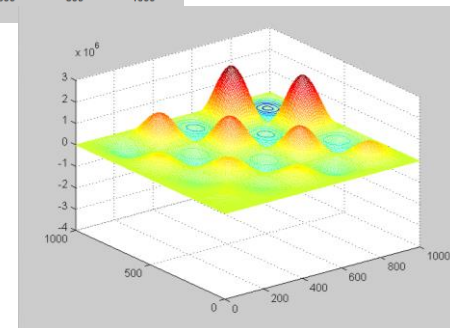
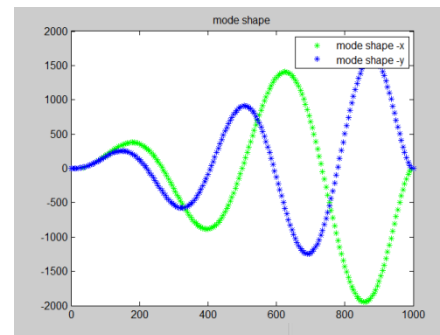
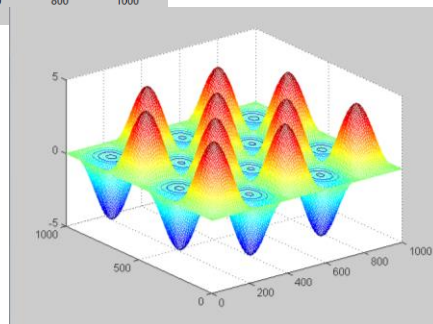
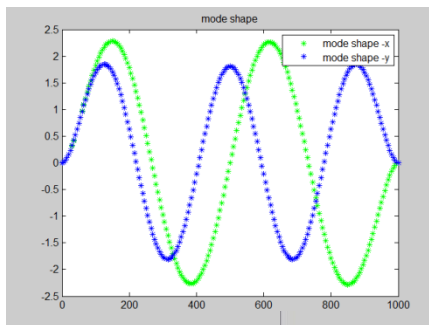
### EIGENFUNCTIONS TEST

$Ae^{\alpha x} Be^{\beta y}$ ,  $Axe^{\alpha x} Be^{\beta y}$ ,  $Aye^{\alpha x} Be^{\beta y}$ ,  $Ay^2 e^{\alpha x} Be^{\beta y}$ ,  $Axye^{\alpha x} Be^{\beta y}$ ,  $Ax^2 e^{\alpha x} Be^{\beta y}$  etc. can not form a basis of the plate's eigenfunction.

$$1) w = Ae^{\alpha x} Be^{\beta y} + Cxe^{\alpha x} De^{\beta y} (+Eye^{\alpha x} Fe^{\beta y})$$

only works for isotropic case

could be a solution of  $\Delta\Delta w = \lambda w$ , but meaningless for plate vibration



## Eigenfunction 2

### NORMAL EIGENFUNCTIONS BASIS

Normal eigenfunction (C=1):

$$w(x, y) = \Phi(x) \psi(y)$$

$$\Phi(x) = -\cos\alpha_1 x + (\beta_1/\alpha_1)k_2 \sin\alpha_1 x + \cosh\beta_1 x - k_2 \sinh\beta_1 x$$

$$\psi(y) = -\cos\alpha_2 y + (\beta_2/\alpha_2)k_1 \sin\alpha_2 y + \cosh\beta_2 y - k_1 \sinh\beta_2 y$$

Self-joint operator:

$$\langle Lw_1, w_2 \rangle = \langle w_1, L^*w_2 \rangle \quad \& L = L^*$$

$$\text{with } \langle Lu, v \rangle = \iint Lu \cdot v dx dy$$

$$\lambda_n - \lambda_m \neq 0 \Rightarrow \langle w_n, w_m \rangle = 0$$

An orthonormal set in a Hilbert space is an orthonormal basis in this Hilbert space.

1. Norm the eigenfunctions
2. The inner product  $\langle w_1, w_2 \rangle$  form a vector space W?
3. This W is complete (Hilbert space)?

## Eigenfunction 2

### INNER PRODUCT

$$L = D_1 \frac{\partial^4}{\partial x^4} + 2D_3 \frac{\partial^4}{\partial x^2 \partial y^2} + D_2 \frac{\partial^4}{\partial y^4}$$

Assuming  $w_1$  &  $w_2$  two function satisfy  $Lw = \lambda w$  and the boundary conditions  $w = \frac{\partial w}{\partial x} = 0$  for  $x=0,a$  and  $w = \frac{\partial w}{\partial y} = 0$  for  $y=0,b$

Strain energy for orthotropic plate:

$$\begin{aligned} U &= \frac{1}{2} \iint D_1 \left( \frac{\partial^2 w}{\partial x^2} \right)^2 + 2D_{12} \frac{\partial^2 w}{\partial x^2} \frac{\partial^2 w}{\partial y^2} + D_2 \left( \frac{\partial^2 w}{\partial y^2} \right)^2 + 4D_{66} \left( \frac{\partial^2 w}{\partial x \partial y} \right)^2 dx dy \\ &= \frac{1}{2} \iint \left[ D_1 \left( \frac{\partial^2 w}{\partial x^2} \right)^2 + 2D_3 \left( \frac{\partial^2 w}{\partial x \partial y} \right)^2 + D_2 \left( \frac{\partial^2 w}{\partial y^2} \right)^2 \right] + (D_1 \vartheta_{21} + D_2 \vartheta_{12}) \left[ \frac{\partial^2 w}{\partial x^2} \frac{\partial^2 w}{\partial y^2} - \left( \frac{\partial^2 w}{\partial x \partial y} \right)^2 \right] dx dy \end{aligned}$$

Strain energy for orthotropic plate:

$$U = \frac{1}{2} \iint D \left( \left( \frac{\partial^2 w}{\partial x^2} \right)^2 + 2\vartheta \frac{\partial^2 w}{\partial x^2} \frac{\partial^2 w}{\partial y^2} + \left( \frac{\partial^2 w}{\partial y^2} \right)^2 + 2(1 - \vartheta) \left( \frac{\partial^2 w}{\partial x \partial y} \right)^2 \right) dx dy$$

$$\langle u, v \rangle = \iint Lu \cdot v dx dy$$

$$\langle w, w \rangle = \iint Lw \cdot w dx dy \text{ is the bending energy?}$$



# Eigenfunction 2

## INNER PRODUCT

$$\begin{aligned}
 \langle w, w \rangle &= \iint Lw \cdot w \, dx dy \\
 &= \iint \left( D_1 \frac{\partial^4 w}{\partial x^4} + 2D_3 \frac{\partial^4 w}{\partial x^2 \partial y^2} + D_2 \frac{\partial^4 w}{\partial y^4} \right) w dx dy \\
 \int \int \frac{\partial^4 w}{\partial x^4} w \, dx dy &= \int \left[ \frac{\partial^3 w}{\partial x^3} w \Big|_{x=0,a} - \int \left( \frac{\partial^3 w}{\partial x^3} \frac{\partial w}{\partial x} \right) dx \right] dy = - \int \left[ \int \left( \frac{\partial^3 w}{\partial x^3} \frac{\partial w}{\partial x} \right) dx \right] dy \\
 &= - \int \left[ \frac{\partial^2 w}{\partial x^2} \frac{\partial w}{\partial x} \Big|_{x=0,a} - \int \left( \frac{\partial^2 w}{\partial x^2} \frac{\partial^2 w}{\partial x^2} \right) dx \right] dy = \int \left[ \int \left( \frac{\partial^2 w}{\partial x^2} \frac{\partial^2 w}{\partial x^2} \right) dx \right] dy \\
 \int \int \frac{\partial^4 w}{\partial y^4} w \, dx dy &= \int \left[ \frac{\partial^3 w}{\partial y^3} w \Big|_{y=0,b} - \int \left( \frac{\partial^3 w}{\partial y^3} \frac{\partial w}{\partial y} \right) dx \right] dy = - \int \left[ \int \left( \frac{\partial^3 w}{\partial y^3} \frac{\partial w}{\partial y} \right) dx \right] dy \\
 &= - \int \left[ \frac{\partial^2 w}{\partial y^2} \frac{\partial w}{\partial y} \Big|_{y=0,b} - \int \left( \frac{\partial^2 w}{\partial y^2} \frac{\partial^2 w}{\partial y^2} \right) dx \right] dy = \int \left[ \int \left( \frac{\partial^2 w}{\partial y^2} \frac{\partial^2 w}{\partial y^2} \right) dx \right] dy
 \end{aligned}$$

## Eigenfunction 2

### INNER PRODUCT

$$\begin{aligned} \iint \frac{\partial^4 w}{\partial x^2 \partial y^2} w \, dx dy &= \int \left[ \frac{\partial^3 w}{\partial x \partial y^2} w \Big|_{x=0,a} - \int \left( \frac{\partial^3 w}{\partial x \partial y^2} \frac{\partial w}{\partial x} \right) dx \right] dy = - \int \left[ \int \left( \frac{\partial^3 w}{\partial x \partial y^2} \frac{\partial w}{\partial x} \right) dx \right] dy \\ &= - \int \left[ \frac{\partial^2 w}{\partial x \partial y} \frac{\partial w}{\partial x} \Big|_{y=0,b} - \int \left( \frac{\partial^2 w}{\partial x \partial y} \frac{\partial^2 w}{\partial x \partial y} \right) dy \right] dx = \iint \frac{\partial^2 w}{\partial x \partial y} \frac{\partial^2 w}{\partial x \partial y} \, dx dy \end{aligned}$$

*So, for clamped orthotropic plate:*

$$U = \langle w, w \rangle = \iint Lw \cdot w \, dx dy$$

## Eigenfunction 2

### VECTOR SPACE

$\langle u, v \rangle = \iint Lu \cdot v dx dy$  with the eigenfunctions  $\Phi_m(x)\psi_n(y)$  (orthogonal set) form a vector space?

Three elements:  $w_1 = \sum_m \sum_n A_{mn} \Phi_m \psi_n$ ,  $w_2 = \sum_m \sum_n B_{mn} \Phi_m \psi_n$ ,  $w_3 = \sum_m \sum_n C_{mn} \Phi_m \psi_n$  then

$$\langle w_1, w_2 \rangle = \iint Lw_1 \cdot w_2 dx dy = \iint w_1 \cdot Lw_2 dx dy = \langle w_2, w_1 \rangle$$

$$\langle \alpha w_1, w_2 \rangle = \iint L\alpha w_1 \cdot w_2 dx dy = \alpha \iint w_1 \cdot Lw_2 dx dy = \alpha \langle w_1, w_2 \rangle$$

$$\begin{aligned} \langle w_1 + w_2, w_3 \rangle &= \iint L(w_1 + w_2) \cdot w_3 dx dy = \iint (Lw_1 + Lw_2) \cdot w_3 dx dy = \iint Lw_1 \cdot w_3 dx dy + \iint Lw_2 \cdot w_3 dx dy \\ &= \langle w_1, w_3 \rangle + \langle w_2, w_3 \rangle \end{aligned}$$

$$\langle w_1, w_1 \rangle = \iint Lw_1 \cdot w_1 dx dy = \iint \lambda_1 w_1 \cdot w_1 dx dy = \iint \lambda_1 \|w_1\|^2 dx dy \geq 0$$

$$\langle w_1, w_1 \rangle = 0 \Rightarrow w_1 = 0$$

## Eigenfunction 2

### COMPLETENESS OF THE VECTOR SPACE

A normed vector space  $V$  is complete if every Cauchy sequence converges.

Cauchy sequence: for a given  $\varepsilon > 0$  sequence  $w = \sum_m \sum_n A_{mn} \Phi_m \psi_n$  there exist  $M, N$  such as  $m, m' > M$  &  $n, n' > N$ ,  $|\sum_{m'} \sum_{n'} A_{m'n'} \Phi_{m'} \psi_{n'} - \sum_m \sum_n A_{mn} \Phi_m \psi_n| < \varepsilon$ .

